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IV — Introduction to Euclidean Classification

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1 What is Euclidean Classification?

1.1 Introduction

a) Partition and hierarchy

Hierarchical classification: System of nested classes (the paradigm of natural sciences) represented by a hierarchical tree.

- b) Qualities of classification: compactness and separability
- c) Descending (or divisive) classification vs ascending (or agglomerative) classification

1.2 Ascending Hierarchical Classification (AHC) using Variance Criterion

Grouping property: If 2 classes are grouped together, the between–variance decreases from an amount equal to the contribution of the dipole defined by the centers of the 2 grouped classes.

Target Example (see II): Three-class partition \mathcal{A} , \mathcal{B} and \mathcal{C} with between-variance 57.43 (variance of the cloud of 3 mean points (A,B,C) of classes). If \mathcal{A} and \mathcal{B} are grouped, the between-variance of the partition in 2 classes, that is, the variance of the cloud of 2 points (barycenter of A and B, C) is equal to 38.10.

Within-contribution of the pair (A,B): $\frac{n_{AB}}{n} \times (AB)^2 = 19.33$, with $AB^2 = 290$ and $\widetilde{n_{AB}} = \frac{1}{\frac{1}{2} + \frac{1}{1}} = 2/3$ (weight of dipole);

One has: 38.10 = 57.43 - 19.33 (grouping property).

Ascending Hierarchical Classification: starting with the basic objects (one-element classes) proceed to successive aggregations, until all objects are grouped in a single class.

At each step, one groups 2 classes of the current partition.

Euclidean classification:

- 1. Objects = points of Euclidean cloud: distance between objets is Euclidean distance.
- 2. Aggregation index = variance index, that is, the contribution of the dipole associated with the 2 aggregated classes (Ward index).

At each step, the aggregated classes are those which lead to the minimal decrease of the between-variance.

1.3 Basic Algorithm

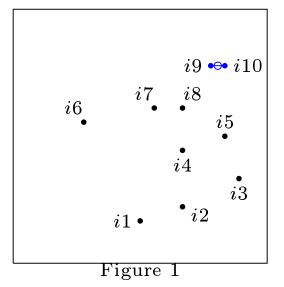
• Step 1. Calculate the contributions of the $9 \times 10/2 = 45$ dipoles

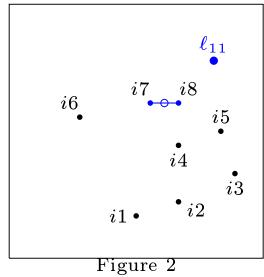
δ	i1	i2	i3	i4	i5	i6	i7	i8	i9
i2	2								
i3	11.6	4							
i4	6.8	3.2	4						
i5	14.4	6.8	2	2					
i6	13	17	27.4	10.6	20.2				
i7	13	10.6	12.2	2.6	5.8	5.2			
i8	14.6	9.8	8.2	1.8	2.6	10	0.8		
i9	29.2	20.8	13.6	8	5.2	19.4	5	2.6	
i10	31.4	21.8	13	9	5	23.2	6.8	3.6	0.2

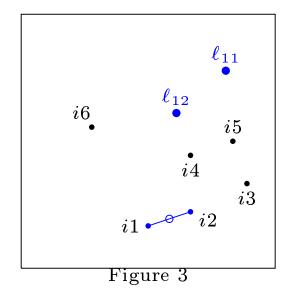
Example: For dipole $\{i1, i2\}$: $\widetilde{n_{12}} = 1/(\frac{1}{1} + \frac{1}{1}) = 0.5$, squared distance= $(0-6)^2 + (-12+10)^2 = 40$, hence the absolute contribution of dipole $\frac{0.5}{10} \times 40 = 2$.

Minimum index 0.2 for the pair of points $\{i9, i10\}$ which are aggregated (fig. 1), hence the mean point $\ell 11$ and a derived *cloud of 9 points* (fig. 2).

New minimum 0.8 for $\{i7, i8\}$ which aggregated (fig. 2), hence the new point $\ell 12$ and a derived *cloud of 8 points* (fig. 3).





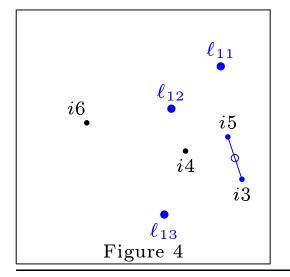


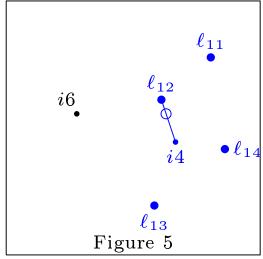
• Step 3. Iterate the procedure

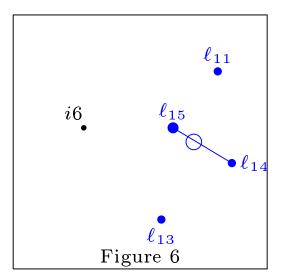
Aggregation index between $\ell 12$ and the 7 other points

	i1	i2	i3	i4	i5	i6	$\ell 11$
$\ell 12$	18.13	13.33	13.33	2.67	5.33	9.87	8.2

Minimum of index = 2 for the three pairs $\{i1, i2\}$, $\{i3, i5\}$ and $\{i4, i5\}$. We choose to aggregate i1 and i2 (fig. 3), hence the point $\ell 13$ and a cloud of 7 points (fig. 4).







^aIn indeterminate cases different choices may yield different classifications.

Aggregation index between $\ell 13$ and the 6 other points

Minimum of index = 2 for the two pairs $\{i3, i5\}$ and $\{i4, i5\}$. We choose to aggregate i3 and i5 (fig. 4), hence the point $\ell 14$ and the cloud of 6 points (fig. 5).

Aggregation index between $\ell 14$ and the 5 other points

2.67 (fig. 5), hence the point $\ell 15$ and the *cloud of 5 points* (fig. 6).

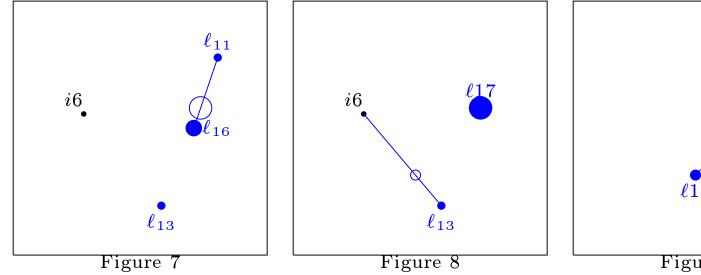
Aggregation index between $\ell15$ and the 4 other points

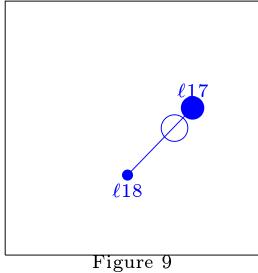
11.33 (fig. 6), hence the point ℓ 16 and the *cloud of 4 points* (fig. 7).

Aggregation index between $\ell 16$ and the 3 other points

	i6	$\ell 11$	$\ell 13$	aggregation	of 16	and	<i>0</i> 11	n t	lovol	15 57	(fig
$\ell 16$	21.67	15.57	20.86	aggregation	01 110	and	LII	au	ievei	10.07	(mg.

 $\overline{7}$), hence the point ℓ 17 and the *cloud of 3 points* (fig. 8).





The three-class partition \mathcal{A} , \mathcal{B} , \mathcal{C} (already studied in II) with mean points A (ℓ 13), B (i6), C (ℓ 17) (fig. 8).

Table of the within-contributions of the 3 pairs of points

$(distance)^2$	weight	Contribution
$AB^2 = 290$	$\widetilde{n_{\rm AB}} = \frac{1}{\frac{1}{2} + \frac{1}{1}} = 2/3$	$Cta_{(A,B)} = \frac{2/3}{10} \times 290 = 19.33$
$AC^2 = 226.33$	$\widetilde{n_{\rm AC}} = \frac{1}{\frac{1}{2} + \frac{1}{7}} = 14/9$	$Cta_{(A,C)} = \frac{14/9}{10} \times 226.33 = 35.21$
$BC^2 = 284.90$	$\widetilde{n_{\mathrm{BC}}} = \frac{\frac{2+7}{1}}{\frac{1}{1} + \frac{1}{7}} = 7/8$	$Cta_{(B,C)} = \frac{7/8}{10} \times 284.90 = 24.93$

At this step, we group A and B at level 19.33 (fig. 9).

Successive steps of the AHC

ℓ	δ_ℓ	classes		n	class description
ℓ 19	38.095	$\ell 18$	$\ell17$	10	<i>i</i> 9 <i>i</i> 10 <i>i</i> 3 <i>i</i> 5 <i>i</i> 4 <i>i</i> 7 <i>i</i> 8 <i>i</i> 6 <i>i</i> 1 <i>i</i> 2
ℓ 18	19.333	$\ell 13$	$\ell 6$	3	$i6\ i1\ i2$
$\ell 17$	15.571	$\ell16$	$\ell 11$	7	$i9\ i10\ i3\ i5\ i4\ i7\ i8$
$\ell 16$	11.333	$\ell15$	$\ell 14$	5	$i3\ i5\ i4\ i7\ i8$
$\ell15$	2.667	$\ell 12$	$\ell 4$	3	$i4\ i7\ i8$
$\ell 14$	2.	$\ell 5$	$\ell 3$	2	$i3\ i5$
$\ell 13$	2.	$\ell 2$	$\ell 1$	2	$i1\ i2$
$\ell 12$	0.8	$\ell 8$	$\ell7$	2	i7~i8
$\ell 11$	0.2	$\ell 10$	$\ell 9$	2	$i9\ i10$

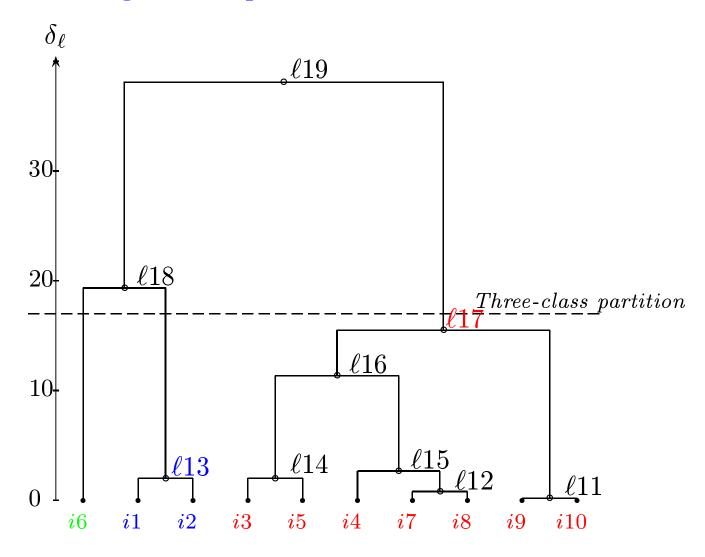
Betv	$Between \mathrm{Var}$				
$\ell 19$	38.10	.414			
$\ell 18$	57.43	.624			
$\ell17$	73.00	.793			
$\ell 16$	84.33	.917			
$\ell15$	87.00	.957			
$\ell 14$	89.00	.967			
$\ell 13$	91.90	.989			
$\ell12$	91.80	.998			
$\ell11$	92.00	1			

The sum of the nine level indices δ_{ℓ} is 92 (total variance of the cloud).

Between-variance of the 2-class partition 38.095.

Between-variance of the 3-class partition 38.095 + 19.333 = 57.43, etc.

Target example: hierarchical tree



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